Amendments to the Specification

Please replace the original specification with the enclosed substitute specification.



OMNI THRUSTER FOR MOTORBOATS AND MOTORYACHTS

FIELD OF INVENTION

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This invention relates to a device for boats, equipped with one or two inboard engines.

DESCRIPTION OF RELATED ART

All types of motor boats have some kind of difficulty when trying to turn around in close quarters and other congested areas, due to the fact that, unlike motor cars that travel on solid ground, boats move and travel on fluid water, where side movement, because of wind and/or current, is not an unusual interference in the operator's intent.

Any additional assistance therefore, to make these maneuvers easier and faster, would always be welcome.

15 BRIEF SUMMARY OF THE INVENTION

The device that we will describe hereunder, will definitely eliminate the above mentioned disadvantage by placing additional lateral forces at the boat's bow and stern, to be used at the discretion of the boat's operator.

This device is a water jet bow and stern thruster, powered by a high velocity water jet pump, driven by the propulsion engine, through a magnetic clutch and operated from the boat's cock-pit by electric switches, as we will see later.

DESCRIPTION OF PRIOR ART

There are in the market bow-thrusters, using electrically, or hydraulically, operated propellers, in a boats bow, which are bulky, requiring large areas to install.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1, is a general plan of a twin inboard engine boat, showing the High Velocity Water Jet Pump (HVWJP), a water jet pump similar to the ones used in the personal water crafts, for

propulsion, but without the gasoline engine driving it, connected to the port engine, through an electromagnetic clutch (EMC), operated from the boat's cock-pit. It also shows the piping connecting the pump to the bow and stern thruster nozzles and solenoid valves that will explain further later.

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Figure 2, is an electrical schematic diagram showing the electrical switches A, B and C on the cock-pit, connecting the four solenoid valves (h), (i), (j) and (k), regulating the jet nozzles.

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Figure 3, is an enlarged view plan of the main switch A, that gives power to either switch B, operating the diagonal turning jets, (h) and (k), or (i) and (j) or, switch C, operating the lateral moving jets, (h) and (j) or (i) and (k). Pilot lights illuminate each switch when energized to show which one is on and the operation it performs.

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Figure 4, is an enlarged plan, showing the intake manifold of the HVWJP and valve (d), that can close the sea water suction C, drawing water from the sea and open suction C2, to pump water from the boat's bilges. It also shows an outlet manifold (f), having a similar valve (e), that diverts the pressure water to a fire manifold (r) This fire hose manifold (r) can, in an emergency, be connected with a special U piece (q), to a pipe (p), leading to main propulsion nozzles (s), at the stern, to be further explained later.

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Figure 5, is an enlarged view plan of switch B, showing the double pole-double throw switch connections to solenoid valves, operating the bow and stern thrusters.

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It also shows the pilot light, illuminating the crossed arrows, indicating the kind of performance this switch is intended to do.

Switch C, is identical to the above switch B, with the difference that on the C, the arrows are parallel.

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DETAILED DESCRIPTION

As in figure 1, the bow and stern thrusters, working in pairs will, either turn the boat quickly to right (clockwise), or to left (counter-clockwise), using switch B, or move the boat sideways, right (starboard direction) or left (port direction), using switch C.

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Figure 3 shows switch A having lighted signals, crossed arrows, when put on one position, indicating the turning movement or, parallel arrows, when put on the second position, indicating the lateral movement.

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Switches B and C give also power, through relays, to the magnetic clutch of the HVWJP, to

come into operation.

Each water jet outlet consists of several nozzles, specially designed to give maximum thrust.

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As in figure 2, pilot lights are also on the switches B and C, indicating which of the two is energized and what operation will perform.

OBJECTS AND ADVANTAGES

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The main advantage of the thruster device of the present invention, over the existing bow thrusters is that the present invention uses, each time, two opposing forces (thrusts), on the two ends of the boat; the action forces on the boat to turn are double and the effect is twice as good

and twice as fast.

Furthermore, using the same equipment we have onboard, if we strike a rock and a leak starts

that the boat's bilge pumps can not maintain, we can turn the HVWJP intake manifold valve (c)

to bilge (c2) and suck the incoming water out from there.

One more advantage, with the equipment onboard is that we can turn, the HVWJP outlet valve

(e), to fire manifold (r), connect a fire hose and fight a fire on board, or on any other boat in the

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vicinity. And finally, if our boat strikes a rock, while speeding, or any other submerged object and the propellers and shafts (i.e., the primary propulsion system) are damaged beyond use, we can install the U section pipe, to connect outlet manifold (r) to pipe (p) and use the HVWJP as auxiliary propulsion and legally avoid being charged with Salvage, instead of Towage, if we need one.

For all above reasons we believe that our thruster device has advantages that the existing bow thrusters do not.

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